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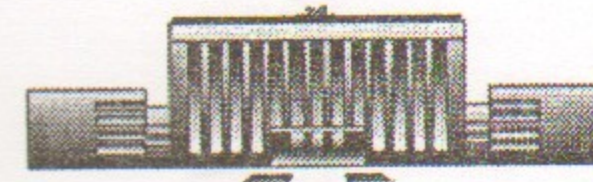
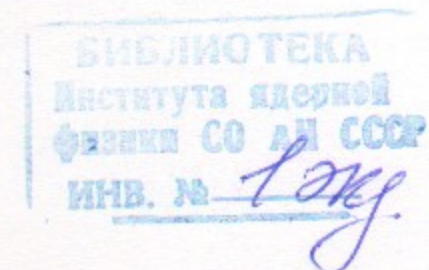
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1998*

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CRITICAL PERTURBATION
IN STANDARD MAP:
A BETTER APPROXIMATION

Budker INP 98-75

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Novosibirsk
1998

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**Critical perturbation in standard map:
A better approximation**

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Abstract

Direct computation of the transition time between neighbor resonances in the standard map, as a function of the perturbation parameter K , allows for improving the accuracy of the critical perturbation value up to $K_{cr} - K_g < 2.5 \times 10^{-4}$ that is by a factor of about 50 as compared to the previous result due to MacKay and Percival.

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As is well known by now a typical structure of the phase space of a few-freedom nonlinear dynamical system is characterized by a very complicated admixture of both chaotic as well as regular (integrable) components of motion (the so-called divided phase space, see, e.g., [1, 2, 3]). Statistical properties of such a motion are very intricate and unusual. One of the most interesting (and important for many applications) problem is the conditions for transition from a local (restricted to relatively small regions in phase space) to the global chaos covering the whole available phase space. The most studied model of such a transition is described by the so-called (canonical) standard map (for history of this model see [4]):

$$\bar{y} = y - \frac{K}{2\pi} \cdot \sin(2\pi x) \quad , \quad \bar{x} = x + \bar{y} \quad (1)$$

where K is the perturbation parameter. In this simple model the transition to global chaos corresponds to some exact critical value $K = K_{cr}$. For $K > K_{cr}$ the motion becomes infinite (in momentum y) for some initial conditions while for $K \leq K_{cr}$ all the trajectories are confined within a period of map (1): $\Delta y = 1$.

The first idea how to solve this difficult problem was due to Greene [5]. First, he was able to solve a much simpler problem of the critical perturbation $K(r)$ at which a particular invariant Kolmogorov - Arnold - Moser (KAM) curve with the rotation number r is destroyed. Critical function $K(r)$ is extremely singular with big dips at everywhere dense set of rational r values (see, e.g., [6]). The physical mechanism of this behavior (known since Poincaré) is explained by resonances in the system (1) as the rotation number is the ratio of oscillation/perturbation frequencies. Whence, the main Greene's idea: to find the 'most irrational' $r = r_g$ which would correspond to the motion 'most far-off' all the resonances. The former is well known in the number theory: $r_g = [111\dots] = (\sqrt{5} - 1)/2$ where the first representation

is a continued fraction. This 'golden' curve was found to be critical at the parameter $K = K_g = 0.97163540631\dots$ [5, 7]. It was conjectured that for $K > K_g$ all invariant curves are destroyed [7], that is $K_{cr} = K_g$.

The 'most-irrational' assumption - as plausible as it is - remains a hypothesis. The main difficulty is here in that the resonance interaction and overlap, destroying invariant curves, depend not only on the resonance spacings, which are indeed maximal for $r = r_g$, but also on the amplitudes of those which are not simply an arithmetical property. Another argument, based on the analysis of the critical function $K(r)$ [8, 9], also does not prove this principal hypothesis.

A different approach to the problem - the so-called converse KAM theory - was developed in [10, 11]. It relies upon a rigorous criterion for the absence of any invariant curve in a certain region. Unfortunately, this criterion can only be checked numerically, and besides it provides the upper bound K_{cr}^+ only (the lower bound $K_{cr}^- = K_g$). The remaining gap, or the accuracy of K_{cr} :

$$(\Delta K)_{cr} = K_{cr}^+ - K_{cr} \quad (2)$$

can be made arbitrarily small at the expense of computation time t_C which scales as [10]

$$t_C \propto (K_{cr}^+ - K_{cr})^{-p} \quad (3)$$

Facing this difficulty, it is natural to recall the first method for calculating the critical perturbation used in [1]. The method was based on the direct computation of trajectories for different $K \rightarrow K_g$. The criterion of supercriticality of a particular K value was very simple: the transition if only a single trajectory in one of two neighbor integer resonances ($y_r = 0 \pmod{1}$) through the destroyed critical curve. With the computers available at that time the minimal $K = 1$ has been reached only which corresponds to the uncertainty $(\Delta K)_{min} = K_{min} - K_g = 0.0284$. This may be compared to the later result $(\Delta K)_{min} = 0.0127$ [10].

Remarkably, the dependence of the average transition time on parameter K was found to be similar to scaling (3):

$$\langle t \rangle = \frac{A}{(K - K_{cr})^p} \quad (4)$$

Fitting three unknown parameters gave: $A = 103$, $p = 2.55$, and $K_{cr} = 0.989$. The latter result was rather different from the present value $K_{cr} \approx K_g$, again because of the computation restrictions mentioned above: $K \geq 1$, $t \leq 10^7$ iterations. Nevertheless, the fitting Eq.(4) provided a less uncertainty

$(\Delta K)_f = K_f - K_g = 0.0174$ as compared to the result from the minimal K . The same is true for data from [10] where $(\Delta K)_f = K_f - K_g = 0.00236$. The latter value was apparently obtained by the direct fitting the relation (3). Fitting in log-log scale provides a much better result: $(\Delta K)_f = K_f - K_g = -0.000128 \pm 0.000288$ that is the remaining uncertainty reduces down to 0.000288.

In both cases the fitted value for the critical perturbation K_{cr} is only true up to a certain confidence probability while the minimal K is an exact result: $K_{cr}^+ = K_{min}$.

In the present paper the studies [1] are continued with much better computers. The main result is farther considerable increasing of the accuracy $(\Delta K)_{cr}$.

To reduce the computation expenses, the transition time was calculated for a number of trajectories N_{tr} started near the unstable fixed point of a half-integer resonance ($y_r = 1/2 \pmod{1}$), and then run until each of them crossed over to a neighbor integer resonance.

The minimal K value is determined already by the first trajectory escaped from the half-integer resonance. In this way the minimal uncertainty

$$(\Delta K)_{min} = K_{min} - K_g = 0.00025 \quad (5)$$

has been achieved with the escape time $t \approx 6.77 \times 10^{11}$ iterations which took about 72 hours of CPU time on ALPHA-4100 computer (see Fig.1).

The average transition time was computed from $N_{tr} = 400$ trajectories for each of 100 values of K in the interval: $0.0035 \leq K - K_g \leq 0.35$. This costed 36 hours of computation. The results are shown in Fig.1. In the whole interval of ΔK the dependence $\langle t(K) \rangle$ is not exactly a power-law. It becomes so asymptotically for $K \rightarrow K_{cr}$ as expected from the theory [12]. For this reason, only few smallest K values of the function $\langle t(K) \rangle$ were taken for the final fitting which is also shown in Fig.1 by the solid line. It is obtained from the fitting 15 left-most points (just up to the first big fluctuation) in log-log scale, and corresponds to the following parameters in Eq.(4):

$$(\Delta K)_f = 0.000125 \pm 0.000267, \quad p = 2.959 \pm 0.0771, \quad A = 33 \pm 8 \quad (6)$$

The fitting relative accuracy $rms = 0.071$ is close to, but somewhat larger than, the standard $rms = 1/\sqrt{N_{tr}} = 0.05$. This is seen from the data of 3 single trajectories in Fig.1, too. Notice also 2 very big deviations for the average over 400 trajectories which nature remains unclear. Interestingly, the relative fitting accuracy of the data [10] is considerably higher: $rms = 0.02$.

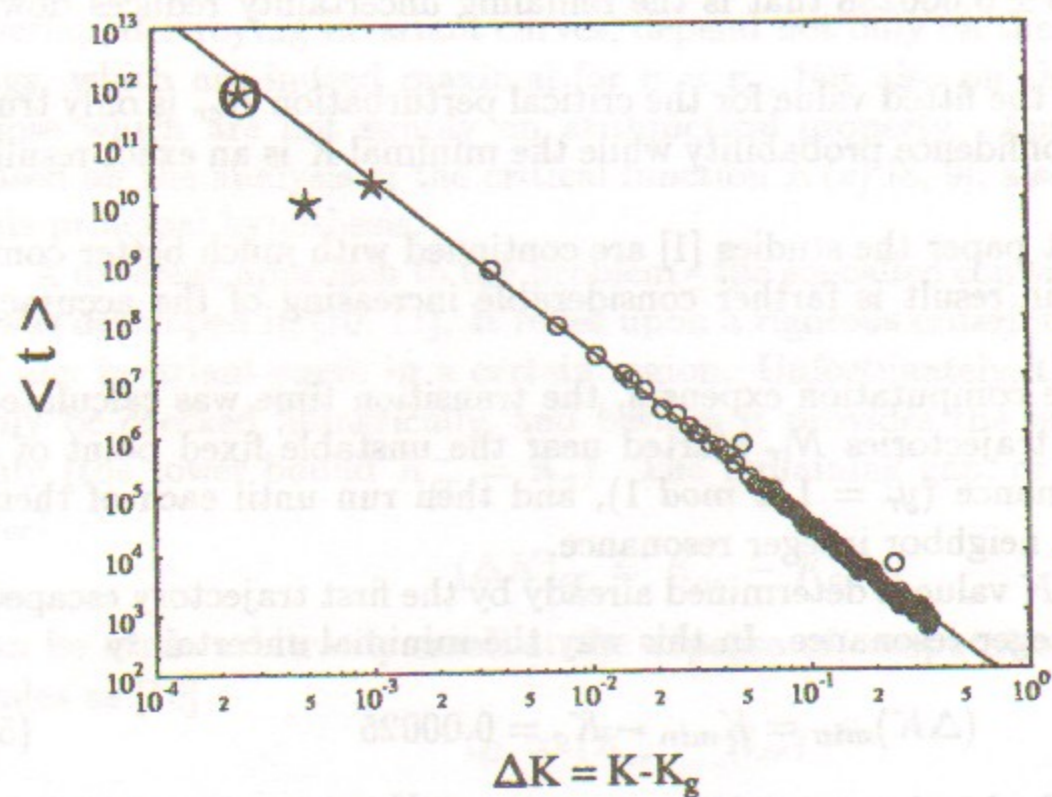


Figure 1: Direct computation of K_{cr} in standard map: average transition time through the destroyed critical curve vs. supercriticality. Circles show numerical results for $N_{tr} = 400$; stars represent 3 single-trajectory runs, including one with the minimal ΔK (5); straight line is relation (4) with parameters (6) fitted from 15 left-most points (circles).

This would require as many as about 5000 trajectories in the present method. However, it does not mean that the computation of the procedure in [10] would be shorter.

The most important parameter in (6) is $(\Delta K)_f$ which is zero within statistical errors. This further confirms the Greene hypothesis $K_{cr} = K_g$. The exponent p is also equal to the theoretical value $p_{th} = 3.011722$ [12] to the fitting accuracy. The present value of parameter A is much less than in [1] because of a different (shorter) transition between resonances used. The summary of all results is presented in the Table below.

Table. Accuracy of K_{cr} in standard map

$(\Delta K)_{min}$ exact	$(\Delta K)_{fit}$ probable	Reference
2.84×10^{-2}	1.74×10^{-2}	[1]
1.27×10^{-2}	3.36×10^{-3}	[10]
	$\pm 1. \times 10^{-3}$	
	-1.28×10^{-4}	[10]
	$\pm 2.88 \times 10^{-4}$	our fit
2.5×10^{-4}	1.25×10^{-4}	present
	$\pm 2.67 \times 10^{-4}$	paper

A serious difficulty in such a numerical approach to the problem is the computation accuracy. This was mentioned also in [10] but no estimate for the computation errors was given, apparently because of a very complicated numerical procedure. Even in a much simpler method [1], accepted in the present study, the effect of noise turned out to be rather complicated. Special numerical experiments were done to clarify the question. To this end, a random perturbation of amplitude ν was introduced in both equations (1). The results are shown in Fig.2.

Typically, the transition time becomes less than that without noise, and saturates below some critical noise-dependent value of K : $\Delta K \lesssim B(\nu)$. However, in some cases the average transition time considerably grows, as an example in Fig.2 demonstrates, apparently due to a sharp increase of the fluctuations near the crossover from normal (noise-free) dependence of $\langle t(\Delta K) \rangle$ to the saturation. In turn, these fluctuations are apparently explained by the noise-induced diffusion into some of many small domains of regular motion within the critical structure.

A rough estimate for unknown function $B(\nu)$ can be obtained as follows. The transition time is primarily determined by the width $\delta y \sim (\Delta K)^2$ of the chaotic layer around destroyed critical curve [12, 13, 3] while the diffusion time through this layer $t_0 \sim 1/\Delta K$ [14, 13, 15, 16]. Noise decreases this time down to $t_\nu \sim (\delta y)^2/\nu^2$. Hence, the crossover corresponds to $t_\nu \sim t_0$, whence:

$$B(\nu) \approx A \cdot \nu^b \quad (7)$$

with $b = 2/5$. Fitting the empirical data in Fig.2 in log-log scale gives: $b \approx 0.39 \pm 0.012$, which is surprisingly close to the theoretical estimate, and $A \approx 0.9716 \pm 0.054$ (Fig.3). The fitting accuracy is also fairly good: the relative $rms = 0.019$. Moreover, below crossover ($\Delta K < B(\nu)$) the width δy as well as the diffusion time depend on ν only, and hence the transition

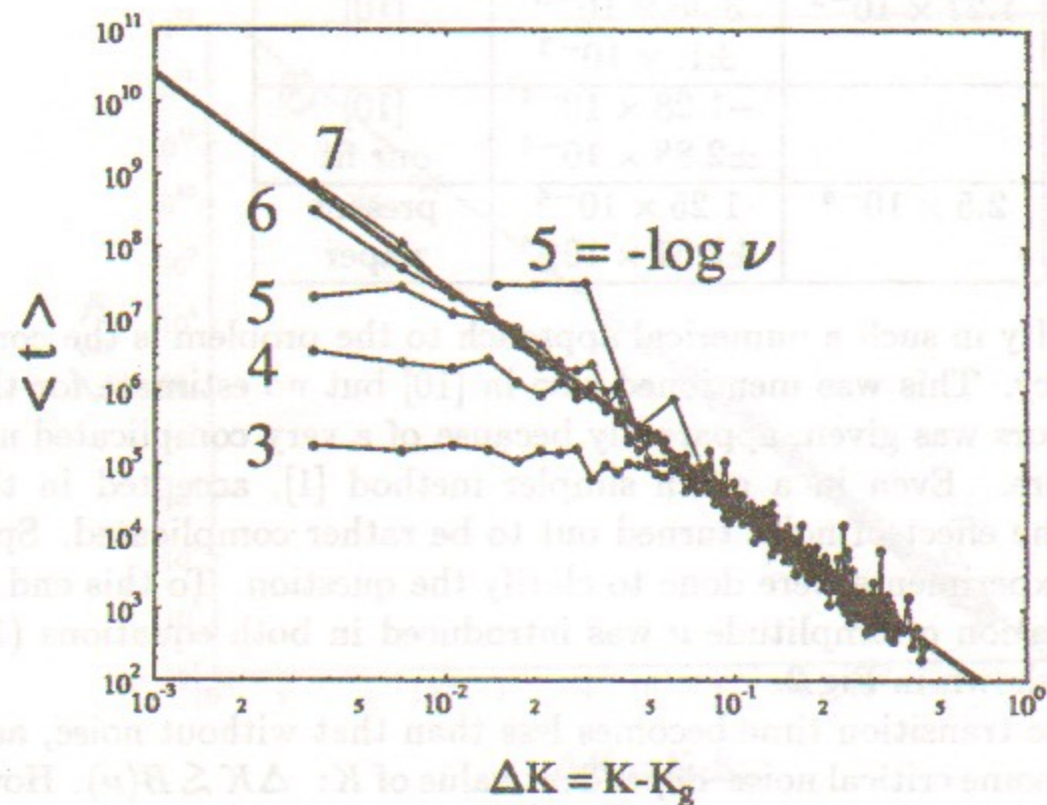


Figure 2: The effect of noise on the supercritical transition time: straight line is the fit of the noise-free computation results (cf. Fig.1); points connected by lines represent the impact of noise with amplitude ν computed for $N_{tr} = 10$; numbers at lines are $-\log(\nu)$ values (logarithm decimal).

time remains approximately constant for a given ν (Fig.2). In any event, the minimal $(\Delta K)_{min}$ (5), which is the main result of the present study, is well above the expected limitation for the double-precision computation (see Fig.3).

In conclusion, the direct approach *a la* [1] to the problem of the critical perturbation in the standard map does further confirm Greene's hypothesis $K_{cr} = K_g$ with a much better exact upper bound (5): $K_{cr} - K_g < 2.5 \times 10^{-4}$.

Still another recent confirmation of this conjecture (curiously, with roughly the same statistical accuracy (6)) has been inferred from a detailed study of the critical structure at the chaos-chaos border in standard map for $K = K_g$ [16].

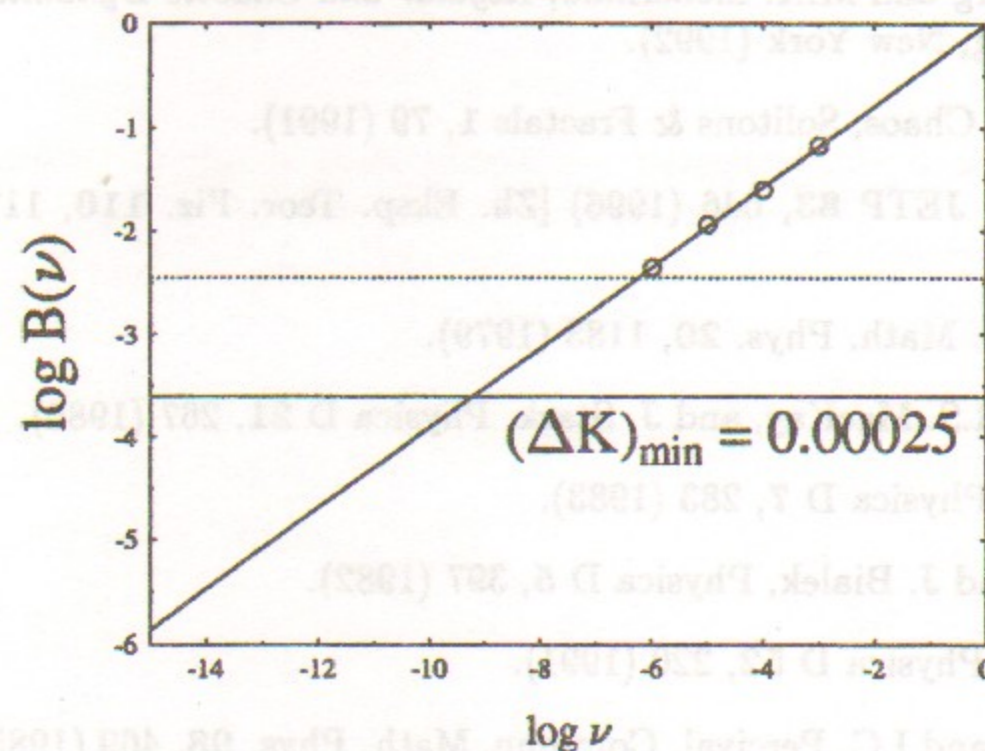


Figure 3: Noise scaling: circles give the empirical crossover values $B(\nu)$ as a function of noise amplitude ν connected and extrapolated by the straight line (7); the upper horizontal dotted line shows the minimal ΔK in computation with noise while the lower line indicates $(\Delta K)_{min}$ (5) achieved in the main double-precision computation (see Fig.1) with the accuracy roughly corresponding to $\log(\nu) \approx -15$; all logarithms are decimal.

Acknowledgements. I am grateful to D.L. Shepelyansky for interesting discussions. This work was partially supported by the Russia Foundation for Fundamental Research, grant 97-01-00865.

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Ответственный за выпуск А.М. Кудрявцев

Работа поступила 14.10.1998 г.

Сдано в набор 20.10.1998 г.

Подписано в печать 20.10.1998 г.

Формат бумаги 60×90 1/16 Объем 0.8 печ.л., 0.7 уч.-изд.л.

Тираж 130 экз. Бесплатно. Заказ № 75

Обработано на IBM PC и отпечатано на
ротапринте ИЯФ им. Г.И. Будкера СО РАН

Новосибирск, 630090, пр. академика Лаврентьева, 11.